

The rotation matrix, \mathbf{W} , used in lattice_symmetry.h

The counterclockwise rotation of a vector \mathbf{r} through a counterclockwise angle Φ about the normalized axis $\hat{\mathbf{t}}$ is treated geometrically, *e.g.*, by Goldstein (1980). Eq. 4-92 in that text gives the formula for the rotated vector,

$$\mathbf{r}' = \mathbf{r} \cos \Phi + \hat{\mathbf{t}}(\hat{\mathbf{t}} \cdot \mathbf{r})[1 - \cos \Phi] + (\hat{\mathbf{t}} \times \mathbf{r}) \sin \Phi . \quad (1)$$

Note that Eq. 1 is for a rotating vector in a fixed laboratory frame. We want to express the rotation in the form of a matrix operator \mathbf{W} (Fischer & Koch, 1996), such that $\mathbf{r}' = \mathbf{W}\mathbf{r}$. We expand the formula in (3×3) matrix notation and rearrange:

$$\mathbf{r}' = \left(\mathbf{I} \cos \Phi + \begin{bmatrix} \hat{t}_x^2 & \hat{t}_x \hat{t}_y & \hat{t}_x \hat{t}_z \\ \hat{t}_x \hat{t}_y & \hat{t}_y^2 & \hat{t}_y \hat{t}_z \\ \hat{t}_x \hat{t}_z & \hat{t}_y \hat{t}_z & \hat{t}_z^2 \end{bmatrix} [1 - \cos \Phi] + \begin{bmatrix} 0 & -\hat{t}_z & \hat{t}_y \\ \hat{t}_z & 0 & -\hat{t}_x \\ -\hat{t}_y & \hat{t}_x & 0 \end{bmatrix} \sin \Phi \right) \mathbf{r} . \quad (2)$$

Eq. 2 is identical to one given in Boisen & Gibbs (1990). This can then be specialized for 2-fold rotations by taking $\Phi=180^\circ$, giving the matrix operator

$$\mathbf{W} = \begin{bmatrix} 2\hat{t}_x^2 - 1 & 2\hat{t}_x \hat{t}_y & 2\hat{t}_x \hat{t}_z \\ 2\hat{t}_x \hat{t}_y & 2\hat{t}_y^2 - 1 & 2\hat{t}_y \hat{t}_z \\ 2\hat{t}_x \hat{t}_z & 2\hat{t}_y \hat{t}_z & 2\hat{t}_z^2 - 1 \end{bmatrix} . \quad (3)$$

It is stressed that \mathbf{W} and $\hat{\mathbf{t}}$ are expressed in Cartesian laboratory coordinates rather than crystallographic coordinates.

References

- Boisen, M. B. Jr & Gibbs, G. V. (1990). *Mathematical Crystallography, Reviews in Mineralogy*, Vol. 15 (revised edition). Washington, DC: Mineralogical Society of America.
- Fischer, W. & Koch, E. (1996). In *International Tables for Crystallography, Volume A: Space-Group Symmetry*, 4th revised edition, Hahn, T., ed. Dordrecht: Kluwer Academic Publishers.
- Goldstein, H. (1980). *Classical Mechanics*, 2nd edition. Reading, MA: Addison-Wesley, pp. 164-166.